

WHAT IS CLAIMED IS:

- 1 1. A method for performing virtual examination of an object comprising:
 - 2 performing at least one scan of an object with the object distended by the
 - 3 presence of a contrast agent;
 - 4 performing at least one scan of the object with the object relieved of the
 - 5 contrast agent;
 - 6 converting the scans to corresponding volume datasets comprising a
 - 7 plurality of voxels;
 - 8 performing image segmentation to classify the voxels of each scan into a
 - 9 plurality of categories;
 - 10 registering the volume datasets of each scan to a common coordinate
 - 11 system;
 - 12 displaying at least two of the volume datasets in a substantially
 - 13 simultaneous manner; and
 - 14 performing virtual navigation operations in one of the volume datasets and
 - 15 having the corresponding navigation operations take place in at least one other volume
 - 16 dataset.

- 1 2. The method for performing virtual examination according to claim 1, wherein the
- 2 at least one scan of the distended object includes a transverse scan and a coronal scan of
- 3 the object.

1 3. The method for performing virtual examination according to claim 2, wherein the
2 at least one scan of the relieved object includes a transverse scan and a coronal scan of the
3 object.

1 4. The method for performing virtual examination according to claim 3, wherein the
2 object is a bladder.

1 5. The method of performing virtual examination according to claim 4, wherein the
2 scans are computed tomography scans.

1 6. The method of performing virtual examination according to claim 4, wherein the
2 scans are ultrasound imaging scans.

1 7. The method of performing virtual examination according to claim 4, wherein the
2 scans are magnetic resonance imaging scans.

1 8. The method of performing virtual examination according to claim 7, wherein the
2 contrast agent is urine.

1 9. The method for performing virtual examination according to claim 1, wherein the
2 at least one scan of the relieved object includes a transverse scan and a coronal scan of the
3 object.

1 10. The method for performing virtual examination according to claim 1, wherein the
2 object is a bladder.

1 11. The method of performing virtual examination according to claim 10, wherein the
2 scans are computed tomography scans.

1 12. The method of performing virtual examination according to claim 10, wherein the
2 scans are ultrasound imaging scans.

1 13. The method of performing virtual examination according to claim 10, wherein the
2 scans are magnetic resonance imaging scans

1 14. The method of performing virtual examination according to claim 13, wherein the
2 contrast agent is urine.

1 15. The method of performing virtual examination according to claim 1, further
2 comprising evaluating the at least one scan with the object distended and the at least one
3 scan with the object relieved to identify regions where contrast is more visible in one of
4 said scans and evaluating the scan with more contrast in a region of interest to determine
5 physiological characteristics of the object.

1 16. The method of performing virtual examination according to claim 15, wherein said
2 step of image segmentation includes classifying voxels based on local intensity vectors of
3 the voxels.

1 17. The method of performing virtual examination according to claim 16, wherein the
2 step of image segmentation further includes using a region growing algorithm to identify
3 regions of the object based on the classified voxels.

1 18. The method of performing virtual examination according to claim 1, further
2 comprising partitioning the volume image datasets into a plurality of regions related to the
3 coordinate system.

1 19. The method of performing virtual examination according to claim 18, wherein the
2 plurality of regions include eight regions defined in a three dimensional coordinate system.

1 20. A method for performing virtual examination of an object comprising:
2 performing an imaging scan of the object to acquire image scan data;
3 converting the acquired image scan data to a plurality of voxels;
4 interpolating between the voxels to generate an expanded dataset;
5 performing image segmentation to classify the voxels into a plurality of
6 categories;
7 extracting a volume of the object interior from the expanded dataset;
8 generating a reduced resolution dataset from the expanded dataset;

- 1 storing the expanded dataset in a tree data structure;
- 2 rendering images for the expanded dataset and reduced resolution dataset;
- 3 and
- 4 selecting at least one of the reduced resolution dataset or expanded dataset
- 5 renderings for display.

1 21. The method for performing virtual examination of an object of claim 20, wherein
2 the selecting step comprises:

1 22. The method for performing virtual examination of an object of claim 20, wherein
2 the imaging scan is a computed tomography scan.

1 23. The method for performing virtual examination of an object of claim 20, wherein
2 the imaging scan is a magnetic resonance imaging scan

1 24. The method for performing virtual examination of an object of claim 20, wherein
2 the imaging scan is an ultrasound imaging scan

1 25. The method for performing virtual examination of an object of claim 20, wherein
2 the object is the larynx.

1 26. The method for performing virtual examination of an object of claim 20, wherein
2 the tree structure is a binary space partition tree structure.

1 27. A method of performing virtual angiography comprising:
2 acquiring imaging scan data including at least a portion of the aorta;
3 converting the imaging scan data to a volume representation including a
4 plurality of voxels;
5 segmenting the volume representation to classify the voxels into one of a
6 plurality of categories;
7 analyzing the segmented volume representation to identify voxels
8 indicative of at least a portion of an aneurysm in the aortic wall; and
9 generating at least one closing surface around the voxels indicative of at
10 least a portion of an aneurysm to estimate the contour of the aneurysm.

1 28. The method of performing virtual angiography of claim 27, wherein the imaging
2 scan is a computed tomography scan.

1 29. The method of performing virtual angiography of claim 27, wherein the imaging
2 scan is a magnetic resonance imaging scan.

1 30. The method of performing virtual angiography of claim 27, wherein the
2 segmenting operation classifies voxels in at least the categories of blood, tissue, and
3 calcium deposits.

1 31. The method of performing virtual angiography of claim 27, further comprising
2 estimating the volume of the aneurysm using the generated closing surfaces.

1 32. The method of performing virtual angiography of claim 27, further comprising
2 generating a navigation path through the aortic lumen.

3 33. The method of performing virtual angiography of claim 32, further comprising
4 estimating the length of the aneurysm based on the navigation path.

1 34. A method of performing virtual endoscopy of a blood vessel comprising:
2 acquiring imaging scan data including at least a portion of the vessel;
3 converting the imaging scan data to a volume representation including a
4 plurality of voxels;
5 segmenting the volume representation to classify the voxels into one of a
6 plurality of categories including the categories of blood, tissue, and calcium deposits; and
7 generating a navigation path through the vessel.

1 35. The method of performing virtual endoscopy of claim 34, wherein the vessel is a
2 carotid artery.

1 36. The method of performing virtual endoscopy of claim 34, further comprising the
2 step of determining the diameter of the carotid artery along the navigation path to identify
3 regions of narrowing.

1 37. The method of performing virtual angiography of claim 34, wherein the imaging
2 scan is a computed tomography scan.

1 38. The method of performing virtual angiography of claim 34, wherein the imaging
2 scan is a magnetic resonance imaging scan.

1 39. A method of determining the characteristics of a stent graft using virtual
2 angioscopy, comprising:
3 acquiring imaging scan data including at least a portion of the aorta;
4 converting the imaging scan data to a volume representation including a
5 plurality of voxels;
6 segmenting the volume representation to classify the voxels into one of a
7 plurality of categories;
8 analyzing the segmented volume representation to identify voxels
9 indicative of at least a portion of an aneurysm in the aortic wall;
10 generating at least one closing surface around the voxels indicative of at
11 least a portion of an aneurysm to estimate the contour of the aneurysm;
12 identifying the location of the endpoints of the aneurysm contour;

1 calculating the length between the endpoints of the aneurysm contour to
2 determine the length of the stent graft; and
3 calculating the diameter of the aortic lumen at the endpoints of the
4 aneurysm contour to determine the required outside diameters of the stent graft.

1 40. The method of determining the characteristics of a stent graft of claim 39, further
2 comprising determining the angle of interface of the aneurysm and normal aortic lumen to
3 determine an angular direction of a corresponding end of the stent graft.

1 41. The method of determining the characteristics of a stent graft of claim 39, further
2 comprising locating arterial branches proximate the aneurysm to determine a maximum
3 length of the stent graft.

1 42. The method of determining the characteristics of a stent graft of claim 41, wherein
2 the arterial branches proximate the aneurysm include at least one of the renal and femoral
3 arterial branches.

1 43. The method of determining the characteristics of a stent graft of claim 39, further
2 comprising conducting a virtual biopsy of the aortic region proximate the ends of the
3 aneurysm to determine the nature of the tissue at the anticipated graft interface locations.

1 44. A method of defining a skeleton for a three dimensional image representation of a
2 hollow object formed with a plurality of voxels comprising:

3 identifying a root voxel within the hollow object;
4 generating a distance map for all voxels within the hollow object, the distance map
5 being formed using a 26-connected cubic plate of neighboring voxels having Euclidian
6 weighted distances;
7 identifying voxels having a local maxima in the distance map as endpoints of
8 branches in the hollow object; and
9 for each local maxima voxel, determining a shortest connected path to one of the
10 root voxel or a previously defined shortest path.

1 45. The method of defining a skeleton for a three dimensional image representation of
2 claim 44 further comprising performing multi-resolution data reduction to the three
3 dimensional image representation to generate a reduced data set for the generating and
4 identifying operations.

1 46. The method of defining a skeleton for a three dimensional image representation of
2 claim 44 further comprising centralizing the shortest paths within the respective branches
3 of the object.

1 47. The method of defining a skeleton for a three dimensional image representation of
2 claim 44, wherein the object includes at least one blood vessel.

1 48. The method of defining a skeleton for a three dimensional image representation of
2 claim 44, wherein the object includes the airways of a lung.

1 49. The method of defining a skeleton for a three dimensional image representation of
2 claim 44, wherein the object includes the bladder.

1 50. The method of defining a skeleton for a three dimensional image representation of
2 claim 44, wherein the object includes the spinal cord of a vertebrate animal.

1 51. A method of performing computed assisted diagnosis of a region of interest,
2 comprising:

3 acquiring imaging scan data including at least a portion of the region of
4 interest;

1 converting the imaging scan data to a volume representation including a
2 plurality of voxels, at least a portion of the voxels representing a surface of the region of
3 interest; and

4 analyzing said portion of voxels representing a surface for at least one of a
5 geometric feature and a textural feature indicative of an abnormality.

1 52. The method of performing computed assisted diagnosis according to claim 51,
2 wherein the textural feature is included in a probability density function characterizing a
3 correlation between two voxels of the portion of voxels.

1 53 The method of performing computed assisted diagnosis according to claim 52,
2 wherein the two voxels are adjacent voxels.

1 54. The method of performing computer assisted diagnosis according to claim 52,
2 wherein intensities of said portion of voxels are used to generate an estimate of the
3 probability density function.

1 55. The method of performing computer assisted diagnosis according to claim 54,
2 wherein a plurality of voxel intensities are used to generate a cumulating distribution
3 function of the region of interest and a local cumulating distribution function, and wherein
4 the local cumulating distribution function is compared against the context cumulating
5 distribution function to identify regions of abnormality.

1 56. The method of performing computer assisted diagnosis according to claim 55,
2 wherein a distance is determined between said local cumulating distribution function and
3 said context cumulating distribution function, the distance providing a measure of
4 abnormality.

1 57. The method of performing computer assisted diagnosis according to claim 56,
2 wherein the distance is used to assign intensity values to the voxels representing a surface
3 of the region of interest and wherein said method further comprises displaying said voxels
4 such that variations in intensity represent regions of abnormality.

1 58. The method of performing computer assisted diagnosis according to claim 57,
2 wherein the region of interest includes the colon and wherein the abnormality includes
3 polyps.

1 59. The method of performing computer assisted diagnosis according to claim 51,
2 wherein the region of interest includes the aorta and wherein the abnormality includes
3 abdominal aortic aneurysms.

1 60. The method of performing computer assisted diagnosis according to claim 51
2 wherein the surface is represented as a second differentiable surface where each surface
3 volume unit has an associate Gauss curvature and wherein said Gauss curvatures combine
4 to form said geometric features.

1 61. The method of performing computer assisted diagnosis according to claim 59
2 wherein a plurality of predetermined geometrical feature templates are defined and
3 wherein the geometric features of said surface are compared to said templates to determine
4 a geometric feature classification.